Entanglement entropy of the large N Wilson-Fisher conformal field theory

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Abstract

We compute the entanglement entropy of the Wilson-Fisher conformal field theory (CFT) in 2+1 dimensions with O(N) symmetry in the limit of large N for general entanglement geometries. We show that the leading large N result can be obtained from the entanglement entropy of N Gaussian scalar fields with their mass determined by the geometry. For a few geometries, the universal part of the entanglement entropy of the Wilson-Fisher CFT equals that of a CFT of N massless scalar fields. However, in most cases, these CFTs have a distinct universal entanglement entropy even at $N = \infty$. Notably, for a semi-infinite cylindrical region it scales as N^0 , in stark contrast to the N-linear result of the Gaussian fixed point.

I. INTRODUCTION

The entanglement entropy (EE) has emerged as an important tool in characterizing strongly interacting quantum systems [1–10]. In the context of relativistic theories in 2 spatial dimensions, the so-called F theorem uses the EE on a circular disk to place constraints on allowed renormalization group flows [9, 11–16]. For quantum systems with holographic duals, the EE can be computed via the Ryu-Takayanagi formula [2], and this is a valuable tool in restricting possible holographic duals of strongly interacting theories [17, 18].

Despite its importance, the list of results for the EE of strongly interacting gapless field theories in 2+1 dimensions is sparse. The most extensive results are for CFTs on a circular disk geometry in the vector large-N expansion [14, 15]. Some results have also been obtained [8] in the infinite cylinder geometry in an expansion in (3 - d), where d is the spatial dimension, but the extrapolation of these results to d = 2 is not straightforward.

In this paper we show how the vector large N expansion can be used to obtain the EE in essentially all entanglement geometries, generalizing results that were only available so far in the circular disk geometry. The large N expansion was also used in Ref. [8] in the infinite cylinder geometry, but the results were limited to the universal deviation in the EE when the CFT is tuned away from the critical point by a relevant operator. CFTs have an EE Swhich obeys

$$S = C\frac{L}{\delta} - \gamma \tag{1}$$

where δ is a short-distance UV length scale, C is a constant depending on the regulator, L is an infrared length scale associated with the entangling geometry, and γ is the universal part of the EE we are interested in. We will compute γ for the Wilson-Fisher CFT with O(N)symmetry or arbitrary smooth regions in the plane, and in the cylinder and torus geometries. Our methods generalize to other geometries, and also to other CFTs with a vector large Nlimit. We also obtain universal entanglement entropies associated with geometries with sharp corners.

Our analysis relies on a general result which will be established in Section II. We consider the large N limit of the Wilson-Fisher CFT on a general geometry using the replica method, which requires the determination of the partition function on a space which is a n-sheeted Riemann surface. The large N limit maps the CFT to a Gaussian field theory with a selfconsistent, spatially dependent mass [8]. Determining this mass for general n is a problem of great complexity, given the singular and non-translationally invariant *n*-sheeted geometry; complete results for such a spatially dependent mass are not available. However, we shall show that a key simplification occurs in the limit $n \to 1$ required for the computation of the EE: the spatially dependent part of the mass does not influence the value of the EE. This simplification leads to the main results of our paper. We note here that simplification does not extend to the Rényi entropies $n \neq 1$: so we shall not obtain any results for the Rényi entropies of the Wilson-Fisher CFT in the large N limit.

Section II will compute the EE for the Wilson-Fisher CFT on arbitrary smooth regions in an infinite plane, and for regions containing a sharp corner, in which case (1) is modified. In both these cases, and for other entangling regions in the infinite plane, the EE is equal to that of a CFT of N free scalar fields. Section III will consider the case of an entanglement cut on an infinite cylinder. A non-zero limit of γ/N as $N \to \infty$ was obtained in Ref. [8] for the free field case. We will show that a very different result applies to the Wilson-Fisher CFT, with $\gamma/N = \mathcal{O}(1/N)$. Section IV considers the case of a torus with two cuts: here γ/N is non-zero for both the free field and Wilson-Fisher cases, but the values are distinct from each other.

II. MAPPING TO A GAUSSIAN THEORY

In this section we consider the EE of the critical O(N) model at large-N, and show that it can be mapped to the entropy of a Gaussian scalar field.

A. Replica method

We first recall how the EE can be computed in a quantum field theory using the replica method introduced in Refs. [1, 19]. The EE associated with a region A is given by

$$S = -\mathrm{Tr}\left(\rho_A \log \rho_A\right) \tag{2}$$

where ρ_A is the reduced density matrix in A. A closely related measure of the entanglement is the Rényi entropies, which are defined as

$$S_n = \frac{1}{1-n} \log \operatorname{Tr} \rho_A^n \tag{3}$$

where n > 1 is an integer. In the replica method, outlined below, the Rényi entropies are directly computed from a path integral construction. One can then analytically continue nto non-integer values, and obtain the EE as a limit

$$\lim_{n \to 1} S_n = S \tag{4}$$

Equivalently, one can consider expanding $\log \operatorname{Tr} \rho_A^n$ to leading order in (n-1), obtaining

$$\log \operatorname{Tr} \rho_A^n = -(n-1)S + \mathcal{O}\big((n-1)^2\big)$$
(5)

Thus, the small (n-1) behavior of $\operatorname{Tr} \rho_A^n$ is sufficient to compute the entropy S.

The computation of $\operatorname{Tr} \log \rho_A^n$ proceeds as follows. We first consider the matrix element of the reduced density matrix between two field configurations on A, $\phi'_A(\mathbf{x})$ and $\phi''_A(\mathbf{x})$. This can be computed using the Euclidean path integral

$$\langle \phi_A'(\mathbf{x}) | \rho_A | \phi_A''(\mathbf{x}) \rangle = \mathcal{Z}_1^{-1} \int_{\phi(\mathbf{x} \in A, t_E = 0^-) = \phi_A'(\mathbf{x})}^{\phi(\mathbf{x} \in A, t_E = 0^+) = \phi_A''(\mathbf{x})} \mathcal{D}\phi(\mathbf{x}, t_E) e^{-\mathcal{S}_E}$$
(6)

where S_E is the Euclidean action of the system. We then write the trace over ρ_A^n in terms of these matrix elements

$$\operatorname{Tr}\rho_{A}^{n} = \int \mathcal{D}\phi_{A}^{\prime} \mathcal{D}\phi_{A}^{\prime\prime} \cdots \mathcal{D}\phi_{A}^{(n)} \langle \phi_{A}^{\prime} | \rho_{A} | \phi_{A}^{\prime\prime} \rangle \langle \phi_{A}^{\prime\prime} | \rho_{A} | \phi_{A}^{\prime\prime\prime} \rangle \cdots \langle \phi_{A}^{(n)} | \rho_{A} | \phi_{A}^{\prime} \rangle$$
(7)

Combining Eqns. (6) and (7), we obtain the path integral expression for $\text{Tr}\rho_A^n$ as

$$\mathrm{Tr}\rho_A^n = \frac{\mathcal{Z}_n}{\mathcal{Z}_1^n} \tag{8}$$

Here, \mathcal{Z}_n is the partition function over the *n*-sheeted Riemann surface obtained by performing the integrations in Eq. (7). In particular, we consider *n* copies of our Euclidean field theory, but we glue the spatial region ($\mathbf{x} \in A, t_E = 0^+$) of the *k*th copy to the spatial region ($\mathbf{x} \in A, t_E = 0^-$) of the (k + 1)th copy, repeating until we glue the *n*th copy to the first copy. This construction introduces conical singularities at the boundary of *A*.

B. Entanglement entropy for the O(N) model at large-N

We now specialize to the critical O(N) model in (2+1)-dimensions. We use a non-linear σ model formulation, writing the *n*-sheeted action as

$$S_n = \int d^3 x_n \, \mathcal{L}_n$$
$$\mathcal{L}_n = \frac{1}{2} \phi_\alpha \left(-\partial_n^2 + i\lambda \right) \phi_\alpha - \frac{N}{2g_c} i\lambda \tag{9}$$

Here, d^3x_n and ∂_n^2 denote the integration measure and the Laplacian on the *n*-sheeted Riemann surface, respectively. The field $\lambda(x)$ is a Lagrange multiplier enforcing the local constraint $\phi(x)^2 = N/g_c$. In the $N = \infty$ limit, the path integral is evaluated using the saddle point method:

$$\mathcal{Z}_{n} = \int \mathcal{D}\phi \mathcal{D}\lambda \ e^{-\mathcal{S}_{n}}$$

$$= \int \mathcal{D}\lambda \ \exp\left[-\frac{N}{2} \operatorname{Tr}\log\left(-\partial_{n}^{2} + i\lambda\right) + \frac{N}{2g_{c}}\int d^{3}x \ i\lambda\right]$$

$$\Longrightarrow \log \mathcal{Z}_{n} = -\frac{N}{2} \operatorname{Tr}\log\left(-\partial_{n}^{2} + \langle i\lambda \rangle_{n}\right) + \frac{N}{2g_{c}}\int d^{3}x_{n} \ \langle i\lambda \rangle_{n} + \mathcal{O}(1/N)$$
(10)

In the last equality, the saddle point configuration of the field λ is determined by solving the gap equation

$$G_n(x,x;\langle i\lambda\rangle_n) = \frac{1}{N} \langle \phi(x)^2 \rangle_n = \frac{1}{g_c}$$
(11)

where $G_n(x, x')$ is the Green's function on the *n*-sheeted surface:

$$\left(-\partial_n^2 + \langle i\lambda(x)\rangle_n\right) G_n(x, x'; \langle i\lambda\rangle_n) = \delta^3(x - x')$$
(12)

and the critical coupling is determined by demanding that the gap vanishes for the infinite volume theory on the plane:

$$\frac{1}{g_c} = \int \frac{d^3p}{(2\pi)^3} \frac{1}{p^2}$$
(13)

In the absence of the entangling cut, n = 1, we denote the saddle point value of λ as

$$\left\langle i\lambda\right\rangle_1 = m_1^2 \tag{14}$$

We assume that the one-sheeted geometry is translation-invariant, so m_1 is independent of position. On the infinite plane we have $m_1 = 0$, but we will also consider geometries where one or both dimensions are finite, in which case m_1 becomes a universal function of the geometry of the system determined by

$$G_1(x,x;m_1^2) = \frac{1}{g_c}$$
(15)

On the *n*-sheeted Riemann surface, $\langle i\lambda(x)\rangle_n$ is always a nontrivial function of position, and the exact form of this function depends on the shape of the entangling surface and the number of Riemann sheets *n*. The problem of determining this function can be addressed numerically for fixed n, but for the purposes of obtaining the EE, we only need its spatial dependence to first-order in (n-1). In particular, we assume that we can write

$$\langle i\lambda(x)\rangle_n \approx m_1^2 + (n-1)f(x) \tag{16}$$

for some function of space-time f(x). Then to linear order in N and (n-1), we have

$$-\log \mathcal{Z}_{n} \approx \frac{N}{2} \operatorname{Tr} \log \left(-\partial_{n}^{2} + m_{1}^{2}\right) - \frac{N}{2g_{c}} \int d^{3}x_{n} \ m_{1}^{2} + (n-1) \frac{N}{2} \operatorname{Tr} \left(\frac{f(x)}{-\partial_{1}^{2} + m_{1}^{2}}\right) - (n-1) \frac{N}{2g_{c}} \int d^{3}x \ f(x)$$
(17)

Then using the definition of G_1 and m_1 ,

$$\operatorname{Tr}\left(\frac{f(x)}{-\partial_1^2 + m_1^2}\right) = \int d^3x \ G_1(x, x; m_1^2) f(x) = \frac{1}{g_c} \int d^3x f(x)$$
(18)

implying that that last line of Eq. (17) vanishes, and f(x) does not contribute to the EE. After using $\int d^3x_n = n \int d^3x$, we can write

$$-\log\frac{\mathcal{Z}_n}{\mathcal{Z}_1^n} = \frac{N}{2} \left[\operatorname{Tr}\log\left(-\partial_n^2 + m_1^2\right) - n\operatorname{Tr}\log\left(-\partial_1^2 + m_1^2\right) \right]$$
(19)

This final expression is equal to the quantity $-\log \operatorname{Tr} \rho_A^n$ computed for N free scalars with mass m_1 and the action

$$\mathcal{L}'_{n} = \phi_{\alpha} \left(-\partial_{n}^{2} + m_{1}^{2} \right) \phi_{\alpha} \tag{20}$$

Therefore, the EE of the critical O(N) model at order N is equal to the EE of N free scalar fields, where the free fields have the same mass gap as the O(N) model on the physical, onesheeted surface. Similar results will apply to other large-N vector models. For instance, in Appendix B we follow very similar steps to show that the EE of the fermionic Gross-Neveu model maps to that of N free Dirac fermions. The mass of the free fermions is determined self-consistently by the spatial geometry of the physical single-sheeted spacetime.

C. Entanglement entropy on the infinite plane

We first consider the EE when the system is on the infinite plane. In this case, $m_1 = 0$, and the EE associated with a region A is equal to the EE of N massless free scalars in the same region. One entangling region for which there are known results is the circular disk. According to the F-theorem [9], the universal part of the EE on the disk is given by

$$\gamma_{\rm disk} = F \equiv -\log |\mathcal{Z}_{S^3}| \tag{21}$$

Here, \mathcal{Z}_{S^3} is the finite part of the Euclidean partition function on a three-sphere spacetime. This quantity was computed in Ref. [14] for massless free scalar fields and for the large-N O(N) model, and they were found to be equal at order N in agreement with our arguments here. Explicitly,

$$\gamma_{\rm disk} = \frac{N}{16} \left(2\log 2 - 3\frac{\zeta(3)}{\pi^2} \right)$$
 (22)

where $\zeta(3) \approx 1.202$. Our results also apply to regions with sharp corners, in which case we can make non-trivial checks of our general result, as we now discuss.

1. Entanglement entropy of regions with corners

When region A (embedded in the infinite plane) contains a sharp corner of opening angle θ , the EE of a CFT (1) is modified by a subleading logarithmic correction [20, 21]

$$S = C\frac{L}{\delta} - a(\theta)\log(L/\delta) + \cdots$$
(23)

where the dimensionless coefficient $a(\theta) \ge 0$ is universal, and encodes non-trivial information about the quantum system. Since we work in the infinite plane, according to our analysis above, the large-N value of $a(\theta)$ will be the same as for N free scalars, namely

$$a_{\rm WF}(\theta) = N \, a_{\rm free}(\theta) + \mathcal{O}(N^0) \tag{24}$$

The non-trivial function $a_{\text{free}}(\theta)$ for a single free scalar was studied numerically and analytically by a number of authors for a wide range of angles [20, 22–26]. Interestingly, we can make an analytical verification of the relation (24) in the nearly smooth limit, by virtue of the following identity that holds for any CFT [22, 27, 28]

$$a(\theta \approx \pi) = \frac{\pi C_T}{24} \left(\theta - \pi\right)^2 + \mathcal{O}\left((\theta - \pi)^4\right)$$
(25)

Here, C_T is a non-negative coefficient determining the groundstate two-point function of the stress tensor $T_{\mu\nu}$:

$$\langle T_{\mu\nu}(x)T_{\eta\kappa}(0)\rangle = \frac{C_T}{x^6} \mathcal{I}_{\mu\nu,\eta\kappa}(x)$$
(26)

where $\mathcal{I}_{\mu\nu,\eta\kappa}(x)$ is a dimensionless tensor fixed by conformal symmetry [29]. Eq. (25) was conjectured [22] for general CFTs in two spatial dimensions, and subsequently proved using non-perturbative CFT methods [28]. Now, C_T is the same at the Wilson-Fisher and Gaussian fixed points [30] at leading order in N:

$$C_T^{\rm WF} = N C_T^{\rm free} + \mathcal{O}(N^0) \tag{27}$$

which, when combined with Eq. (25), leads to a non-trivial confirmation of (24) in the nearly smooth limit $\theta \approx \pi$. (We note that $C_T^{\text{free}} = 3/(32\pi^2)$ using conventional normalization [29].)

The knowledge of C_T can be used to make a statement about $a(\theta)$ away from the nearly smooth limit because the existence of the following lower bound [25]: $a(\theta) \geq C_T \frac{\pi^2}{3} \log [1/\sin(\theta/2)]$, which follows from the strong subadditivity of the EE, and (25). We see that applying this bound to the large-N Wilson-Fisher fixed point is consistent with our result (24).

III. INFINITE CYLINDER

We now compute the EE of the semi-infinite region obtained by tracing out half of an infinite cylinder. The relevant geometry is pictured in Fig. 1. We can take the position of the cut to be at x = 0 by translation invariance. As for the disk, we can write the EE as

$$S = C \frac{L}{\delta} - \gamma_{\rm cyl} \tag{28}$$

where γ_{cyl} is the universal part. The existence of a universal γ_{cyl} in critical theories was first established [7, 31, 32] for the z = 2 quantum Lifshitz model using the methods of Ref. [5]. In the context of CFTs, this geometry was considered in Ref. [8], where the entropy γ was computed for massless free fields and for the Wilson-Fisher fixed point in the $\epsilon = 4 - D$ expansion (where the extra dimensions introduced in the ϵ -expansion are made periodic with circumference L).

We first review the calculation of the entropy for free massive fields, which will allow us to calculate the EE for the Wilson-Fisher fixed point for large N. We allow twisted boundary conditions along the finite direction

$$\phi(x, y + L) = e^{i\varphi_y}\phi(x, y) \tag{29}$$

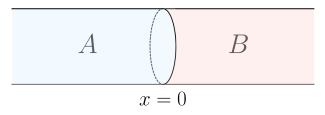


FIG. 1. The geometry considered in calculating the entanglement entropy on the infinite cylinder.

Here, $\varphi_y \in [0, 2\pi)$. We note that unless $\varphi_y = 0, \pi$, the fields ϕ are complex. In this case, we are considering N/2 complex fields, and the O(N) symmetry of the theory breaks down to $U(1) \times SU(N/2)$.

This geometry allows a direct analytic computation of the *n*-sheeted partition function for free fields by mapping to radial coordinates, $(t_E, x) = (r \cos \theta, r \sin \theta)$. In these coordinates, the *n*-sheeted surface is fully parametrized by giving the angular coordinate a periodicity of $2\pi n$. In Refs. [1, 8], it was shown that the *n*-sheeted partition function for free fields can be written in terms of the one-sheeted Green's function:

$$-\log\frac{\mathcal{Z}_n}{\mathcal{Z}_1^n} = \frac{N}{2} \left[\operatorname{Tr}\log\left(-\partial_n^2 + m^2\right) - n\operatorname{Tr}\log\left(-\partial_n^2 + m^2\right) \right]$$
$$= \frac{\pi N}{6} \left(n - \frac{1}{n}\right) LG_1(x, x; m^2)$$
(30)

Then using Eq. (5), the EE is given by

$$S = \frac{\pi N}{3} LG_1(x, x; m^2)$$
(31)

In Appendix A, we compute the Green's function for a massive free field on the cylinder (see also Ref. [33]). Using Eq. (A5), and making the cutoff dependence explicit, we find the regularized part of the EE to be

$$\gamma_{\rm cyl} = \frac{N}{12} \log \left[2 \left(\cosh mL - \cos \varphi_y \right) \right] \tag{32}$$

For $m_1 = 0$, this reduces to Eq. (5.12) of Ref. [8], and indeed displays a divergence for a periodic boundary condition $\varphi_y = 0$ due to the zero mode. We note that the universal contribution to the EE of N/2 complex free scalar fields is of order N, as one would expect from a free field theory with N degrees of freedom.

We now turn to the Wilson-Fisher fixed point. In a finite geometry, the Wilson-Fisher fixed point will acquire a mass gap m_1 which is proportional to 1/L and depends only on

 φ_y . This is computed by solving $G_1(x, x; m_1^2) = 1/g_c$, which is done in Appendix A. The result is

$$m_1 = \frac{1}{L}\operatorname{arccosh}\left(\frac{1}{2} + \cos\varphi_y\right) \tag{33}$$

Then from the arguments of Section II,

$$\gamma_{\rm cyl} = \frac{N}{12} \log \left[2 \left(\cosh m_1 L - \cos \varphi_y \right) \right] = 0 \tag{34}$$

It happens that for the saddle point value of the mass, the universal part of the EE vanishes for all values of the twist φ_y . The leading contribution to γ_{cyl} will be of $\mathcal{O}(N^0)$, a drastic reduction from Gaussian fixed point which is of order N.

This result can be seen more directly from Eq. (31). The gap equation implies that $G_1(x, x; m_1^2) = 1/g_c$, so without even solving for m_1 , the EE can immediately be written

$$S = \frac{\pi N}{3} \frac{L}{g_c} \tag{35}$$

However, the critical coupling is completely non-universal and independent of L. Using a hard UV cutoff $1/\delta$,

$$\frac{1}{g_c} = \int^{1/\delta} \frac{d^3 p}{(2\pi)^3} \frac{1}{p^2} = \frac{1}{2\pi^2 \delta}$$
(36)

and the EE is pure area law, $S \propto L/\delta$.

In fact, this result can be extended to other geometries. The result $\gamma_{cyl} = 0$ for the large- N Wilson-Fisher fixed point occurred because the entropy is proportional to $G_1(x, x; m^2)$. However, the results of Refs. [1, 8] imply that the expression for the free-field entropy given in Eq. (31) holds for *any* system where the entangling cut is perpendicular to an infinite, translationally-invariant direction. Thus, if we consider the large-N Wilson-Fisher CFT on any d-dimensional spatial geometry with at least one infinite dimension, the universal part of the EE obtained by tracing out over half of that dimension is $\mathcal{O}(N^0)$. This argument only holds in dimensions where the Wilson-Fisher CFT exists, so for 1 < d < 3. In particular, this result agrees with the large-N limit of the ϵ -expansion calculation in Ref. [8], which considered the Wilson-Fisher CFT on the $(3 - \epsilon)$ -dimensional spatial region $\mathbb{R} \times \mathbb{T}^{2-\epsilon}$, where \mathbb{T}^d is the d-dimensional torus. This constitutes a non-trivial consistency check on both calculations.

Finally, we note that similar results apply to other large N models. As shown in Appendix B, the EE for the Gross-Neveu CFT maps to that of N free Dirac fermions, where the

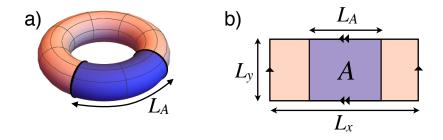


FIG. 2. a) Two dimensional (flat) torus. b) Its representation in the plane. We analyze the entanglement entropy of region A.

mass of the fermions is determined by the spatial geometry of the one-sheeted spacetime, Tr $G_1^F(x, x; m_1) = m_1/g_c^2$. Here, the critical coupling $1/g_c^2$ is again a non-universal quantity which cannot depend on the spatial geometry of the system, and is proportional to the UV cutoff. Then using the results of Ref. [1], it can be shown that $S \propto G_1^F$ for free fermions on the spatial geometries discussed in the previous paragraph, and therefore $\gamma = \mathcal{O}(N^0)$ for the large-N Gross-Neveu CFT on the infinite cylinder.

IV. TORUS

We study the EE of the large-N fixed point on a spatial torus, as shown in Fig. 2. For a general scale invariant theory without a Fermi surface, we expect the following form for S [34, 35]

$$S = C \frac{2L_y}{\delta} - \gamma_{\rm tor}(u;\tau) \tag{37}$$

where we have defined the ratio

$$u = L_A / L_x \tag{38}$$

and τ is the modular parameter, $\tau = iL_x/L_y$, for the rectangular torus we work with. γ_{tor} is a universal term that we shall study at the large-N Wilson-Fisher fixed point.

As discussed in Section IIB, the EE at leading order in N is given by that of N/2 free complex with a mass m_1 determined by the geometry. m_1 is thus the self-consistent mass on the torus for a single copy of the theory, which was recently computed at large N in Ref. [36]. It obeys the scaling relation $m_1L_y = g(\tau)$, where τ is the aspect ratio of the torus, and g is a non-trivial dimensionless function given in Appendix C. m_1 depends on both twists along the x- and y-cycles of the torus, φ_x, φ_y . Since $\gamma_{\text{tor}}^{\text{free}}$ for a massive free boson is not known, we will numerically study the (u, τ) -dependence of $\gamma_{\text{tor}}^{\text{WF}}$ by working on the lattice.

However, before doing so, we describe two limits in which we can make statements about γ_{tor} . First, we consider the so-called thin torus limit for which $L_y \to 0$, while L_A, L_x remain finite, i.e. $\tau \to i\infty$ and u is fixed. For generic boundary conditions, we have that the torus EE approaches twice the semi-infinite cylinder value [34, 35] discussed above, $\gamma_{\text{tor}} \to 2\gamma_{\text{cyl}}$. This holds in the absence of zero modes, which is the generic case. Our result Eq. (34) implies that $\gamma_{\text{tor}} = \mathcal{O}(N^0)$ in that limit. However, this cannot hold at all values of τ . Indeed, for any fixed τ let us consider the "thin slice" limit $L_A \to 0$. There, γ_{tor} reduces to the universal contribution of a thin strip of width L_A in the infinite plane [34, 35], $\gamma_{\text{tor}} = \kappa L_y/L_A$, where the universal constant $\kappa \geq 0$ can be computed in the infinite plane. κ is thus independent of the boundary conditions along x, y. Applying our mapping to free fields, this means that at leading order in N

$$\kappa^{\rm WF} = N \kappa^{\rm free} \tag{39}$$

where $\kappa^{\text{free}} \simeq 0.0397$ for a free scalar [20]. By continuity, we thus expect that for general u and τ , $\gamma_{\text{tor}}^{\text{WF}}$ will scale linearly with N in the large-N limit. We now verify this statement via a direct calculation.

A. Lattice numerics

The lattice Hamiltonian for a free boson of mass m_1 can be taken to be

$$H = \frac{1}{2} \sum_{k_y} \sum_{i=0}^{L_x - 1} \left(|\pi_{k_y}(i)|^2 + |\phi_{k_y}(i+1) - \phi_{k_y}(i)|^2 + \omega_{k_y}^2 |\phi_{k_y}(i)|^2 \right)$$
(40)

$$\omega_{k_y}^2 = 4\sin^2(k_y/2) + m_1^2 \tag{41}$$

where the theory is defined on a square lattice with unit spacing, $\pi_{k_y}(i)$ is the operator canonically conjugate to $\phi_{k_y}(i)$, and $|A|^2 = A^{\dagger}A$. The index *i* runs over the L_x lattice sites in the *x*-direction. Crystal momentum along the *y*-direction remains a good quantum number in the presence of the entanglement cut, and is quantized as follows

$$k_y = \frac{2\pi n_y}{L_y} + \frac{\varphi_y}{L_y}, \qquad (42)$$

where the integer n_y runs from 0 to $L_y - 1$, and φ_y is the twist along the y-direction. We note that the Hamiltonian (40) corresponds to L_y decoupled 1d massive boson chains: $H = \sum_{k_y} H_{1d}(k_y)$, each with an effective mass ω_{k_y} . This means that the EE is the sum over the corresponding 1d EEs: $S = \sum_{k_y} S_{1d}(k_y)$. For each 1d chain, the EE for the interval of length $L_A \leq L_x$ is obtained from the correlation functions $X_{ij} = \langle \phi^{\dagger}(i)\phi(j) \rangle$ and $P_{ij} = \langle \pi^{\dagger}(i)\pi(j) \rangle$, where we have suppressed the k_y label. The prescription for the EE is then [20]

$$S_{\rm 1d} = \sum_{\ell} \left[(\nu_{\ell} + \frac{1}{2}) \log(\nu_{\ell} + \frac{1}{2}) - (\nu_{\ell} - \frac{1}{2}) \log(\nu_{\ell} - \frac{1}{2}) \right]$$
(43)

where ν_{ℓ} are eigenvalues of the matrix $\sqrt{X_A P_A}$, with the A meaning that X_{ij} and P_{ij} are restricted to region A. This method was previously used to study the EE of free fields on the torus [34, 35, 37].

To obtain the universal part of the entropy we first need to numerically determine the area law coefficient C (37), which we find is $C \simeq 0.07745$. We can then isolate the universal part, γ_{tor} , by subtracting the area law contribution. The result for a square torus, i.e. $\tau = i$, is shown in Fig. 3, where we compare the Wilson-Fisher fixed point with the Gaussian fixed point. Only 0 < u < 1/2 is shown because the other half is redundant by virtue of the identity $\gamma_{tor}(1-u) = \gamma_{tor}(u)$, true for pure states. We set $\varphi_x = 0$ and $\varphi_y = \pi$ (since fully periodic boundary conditions lead to a diverging γ_{tor}^{Gauss}), which leads to a purely imaginary mass $m_1 L_y \simeq i 1.77078$ for the Wilson-Fisher theory, while m_1 is naturally zero at the Gaussian fixed point. The imaginary mass does not cause a problem since $k_y^2 + m_1^2 > 0$ in the presence of the twist, (42). From Fig. 3, we find that $\gamma_{\text{tor}}^{\text{WF}}$ scales linearly with N as was anticipated above. However, contrary to the case of the infinite plane, the EE of the Wilson-Fisher fixed point is reduced compared to the Gaussian fixed point, $\gamma_{\text{tor}}^{\text{WF}}(u) < \gamma_{\text{tor}}^{\text{Gauss}}(u)$ for all values of u. The difference between the EE of the two theories decreases in the thin slice limit $u \to 0$, where we have the divergence $\gamma_{tor} = \kappa/u$, with the same constant κ , Eq. (39). This constant has been calculated in different context [20], $N\kappa^{\text{free}} = N 0.0397$, and fits our data very well. Another consistency check is that $\gamma_{tor}(u)$ should be convex decreasing [35] for 0 < u < 1/2, which is indeed the case in Fig. 3.

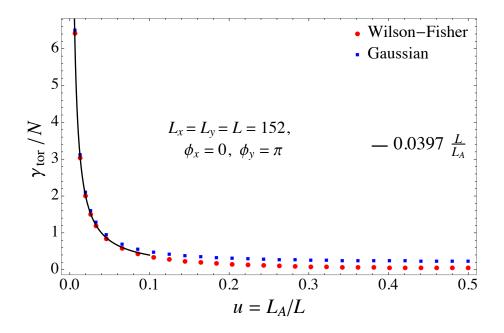


FIG. 3. The universal EE γ_{tor} of a cylindrical region, $L_A \times L$, cut out of a square torus, $L \times L$. The red dots correspond to the interacting fixed point of the O(N) model at large N, while the blue squares to the Gaussian fixed point (N free relativistic scalars). We have normalized γ_{tor} by N. The data points were obtained numerically on a lattice of linear size L = 152. The line shows the expected divergence in the small u limit, the same for both theories.

V. CONCLUSIONS

The large N limit of the Wilson-Fisher theory yields the simplest tractable stronglyinteracting CFT in 2+1 dimensions. In this paper, we have succeeded in computing the entanglement entropy of this theory using a method which can be applied to essentially any entanglement geometry. In particular, for any region in the infinite plane, the EE of the large-N Wilson-Fisher fixed point is the same as that of N free massless bosons. In contrast, when space is compactified into a cylinder or a torus, the results will differ in general as we have illustrated using cylindrical entangling regions. Our results naturally extend to other large-N vector theories, like the fermionic Gross-Neveu CFT (Appendix B).

In the case of the EE of the semi-infinite cylinder, γ_{cyl} , Ref. [8] has compared its value between the UV Gaussian fixed point and the IR Wilson-Fisher one using the epsilon expansion. It was found that $|\gamma_{cyl}^{UV}| > |\gamma_{cyl}^{IR}|$, suggestive of the potential of γ_{cyl} to "count" degrees of freedom. Our results at large N, however, show that the opposite can be true: $\gamma_{cyl}^{UV} \ll \gamma_{cyl}^{IR}$. Indeed, if we consider the flow from the Wilson-Fisher point to the fixed point of the broken symmetry phase, we see that $\gamma_{cyl}^{WF} \sim N^0$, while at the IR fixed point $\gamma_{cyl}^{broken} \sim N$ due to the Goldstone bosons. This holds for generic boundary conditions $\varphi_y \neq 0$.

It is also of interest to obtain the Rényi entropies of such an interacting CFT, notably for comparison with large-scale quantum Monte Carlo simulations which usually only have access to the second Rényi entropy [38, 39]. Unfortunately, this is a much more challenging problem, because the full x-dependence of the saddle-point $\langle i\lambda(x)\rangle_n$ in (12) is needed on a *n*-sheeted Riemann surface. Numerical analysis will surely be required, supplemented by analytic results in the limit of large and small x.

Note: While finishing this work, we became aware of a related forthcoming paper [40] that studies the area law term in a large-N supersymmetric version of the O(N) model.

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Appendix A: Green's function and Large-N mass gap on the cylinder

In Section III, we used the Green's function for a massive scalar on the infinite cylinder. This is given by

$$G_1(x,x;m^2) = \frac{1}{L} \sum_{k_y} \int \frac{d^2 p}{(2\pi)^2} \frac{1}{p^2 + k_y^2 + m^2}$$
(A1)

where we allow a twist in the finite direction

$$k_y = \frac{2\pi n_y + \varphi_y}{L}, \qquad n_y \in \mathbb{Z}$$
 (A2)

We evaluate this expression using Zeta regularization. We first introducing an extra parameter ν , and consider the expression

$$G_1(x,x;m^2) = \frac{1}{L} \sum_{k_y} \int \frac{d^2 p}{(2\pi)^2} \frac{1}{\left(p^2 + k_y^2 + m^2\right)^{\nu}}$$
(A3)

This expression is convergent for $\nu > 3/2$. We evaluate this expression where it is convergent, and then analytically continue it to $\nu \to 1$. After evaluating the integrals, we obtain

$$G_1(x, x; m^2) = \frac{1}{8\pi^2 L \left(\nu - 1\right)} \sum_{k_y} \frac{1}{\left(k_y^2 + m^2\right)^{\nu - 1}}$$
(A4)

The remaining sum needs to be evaluated as a function of ν , which requires the use of generalized Zeta functions. General formulae for sums of this type can be found in Reference [41], and after evaluating this sum and taking $\nu \to 1$, we find

$$G_1(x, x; m^2) = -\frac{1}{4\pi L} \log\left[2\left(\cosh mL - \cos\varphi_y\right)\right] \tag{A5}$$

We note that the original integral, Eq. (A1), has a linear UV divergence which has been set to zero by our cutoff method. In other regularization methods, one generically expects an extra term proportional to the UV cutoff, $G_1(x, x; m^2) \propto 1/\delta$, which contributes to the area law in Eq. (31).

We also find the mass gap for the Wilson-Fisher fixed point at large-N. The gap equation is

$$G_1(x, x; m_1^2) = \frac{1}{g_c}$$
(A6)

However, in Zeta regularization we have

$$\frac{1}{g_c} = \int \frac{d^3 p}{\left(2\pi\right)^2} \frac{1}{p^2} = 0 \tag{A7}$$

Then using Eq. (A5), we find the energy gap on the cylinder

$$m_1 = \frac{1}{L}\operatorname{arccosh}\left(\frac{1}{2} + \cos\varphi_y\right) \tag{A8}$$

as quoted in the main text.

Appendix B: Entanglement entropy of the Gross-Neveu model at large-N

We discuss the Gross-Neveu model [42] in the large-N limit. The calculation of the entanglement entropy is very similar to the critical O(N) model, and we find a mapping to the free fermion entanglement analogous to the mapping derived in Section II.

The critical model is defined by the Euclidean Lagrangian

$$\mathcal{L}_n = -\bar{\psi}_\alpha \left(\partial_n + \sigma \right) \psi_\alpha + \frac{N}{2g_c^2} \sigma^2 \tag{B1}$$

where the repeated index α is summed over, running from 1 to N. Here, $\sigma(x)$ is a Hubbard-Stratonovich field used to decouple the quartic interaction term $(\bar{\psi}_{\alpha}\psi_{\alpha})^2$. We now follow the steps in Eq. (10) to obtain the partition function using the saddle point method.

$$\log \mathcal{Z}_n = N \operatorname{Tr} \log \left(\partial_n + \langle \sigma \rangle_n \right) - \frac{N}{2g_c^2} \int d^3 x_n \, \langle \sigma \rangle_n^2 + \mathcal{O}(1/N) \tag{B2}$$

The saddle point configuration of σ is determined by the Gross-Neveu gap equation

$$\operatorname{Tr} G_n^F(x, x; \langle \sigma \rangle_n) = \frac{\langle \sigma \rangle_n}{g_c^2}$$
$$\left(\partial_n + \langle \sigma(x) \rangle_n \right) G_n^F(x, x'; \langle \sigma \rangle_n) = \delta^3(x - x')$$
(B3)

Here, the trace is over spinor indices and we have left the identity matrix in spinor space implicit. The critical coupling is

$$\frac{1}{g_c^2} = (\operatorname{Tr} \mathbb{I}) \int \frac{d^3 p}{(2\pi)^3} \frac{1}{p^2}$$
(B4)

Following our procedure for the O(N) model, we write the saddle point configuration as

$$\langle \sigma(x) \rangle_n \approx m_1 + (n-1) f(x)$$
 (B5)

to leading order in (n-1), for an unknown function f(x). Then by a similar reasoning to the calculations in Section II, we find

$$-\log\frac{\mathcal{Z}_n}{\mathcal{Z}_1^n} = -N\left[\operatorname{Tr}\log\left(\partial_n + m_1\right) - n\operatorname{Tr}\log\left(\partial_1 + m_1\right)\right]$$
(B6)

This is the *n*-sheeted partition function for N free Dirac fermions with mass m_1 , where m_1 is the mass gap of the Gross-Neveu model on the one-sheeted physical spacetime, Tr $G_1^F(x, x; m_1) = m_1/g_c^2$.

Just as for the O(N) Wilson-Fisher fixed point, we can verify our result for the special case where region A is a disk embedded in the infinite plane. The disk's universal entanglement entropy in the Gross-Neveu CFT was found to be that of N free massless Dirac fermions [14], $\gamma_{\text{disk}} = N \gamma_{\text{disk}}^{\text{free}} + \mathcal{O}(N^0)$. This is exactly our result since $m_1 = 0$ for this geometry.

Appendix C: Mass gap on the torus

In Section IV, we used the self-consistent mass of the large-N Wilson-Fisher fixed point on the torus. This mass takes the form

$$L_y m_1 = g(\tau) \tag{C1}$$

where $g(\tau)$ is a universal function of them modular parameter of the torus, τ , and the twists φ_x and φ_y . The calculation of m_1 was done in Ref. [36]. Here, we outline the results needed for the current work. Unlike Ref. [36], we specialize to the rectangular torus, $\tau = iL_x/L_y$.

The Green's function on the torus is

$$G_{1}(x, x; m_{1}^{2}) = \frac{1}{L_{x}L_{y}} \sum_{k_{x}k_{y}} \int \frac{d\omega}{2\pi} \frac{1}{\omega^{2} + k_{x}^{2} + k_{y}^{2} + m_{1}^{2}}$$
$$= \frac{1}{2L_{x}L_{y}} \sum_{k_{x}k_{y}} \frac{1}{\left(k_{x}^{2} + k_{y}^{2} + m_{1}^{2}\right)^{1/2}}$$
(C2)

where

$$k_x = \frac{2\pi n_x + \varphi_x}{L_x}$$
$$k_y = \frac{2\pi n_y + \varphi_y}{L_y}$$
(C3)

for integers n_x and n_y . As in Appendix A, we evaluate G_1 using Zeta regularization; the technical details of this calculation can be found in Ref. [36]. In this regularization, the gap equation is

$$G_1(x, x; m_1^2) = 0 (C4)$$

After regularizing, we can write the Green's function as

$$4\pi L_y G_1(x,x;m_1^2) = \int_1^\infty d\lambda \ \lambda^{1/2} \exp\left(-\frac{\lambda}{4\pi} \left(L_y^2 m_1^2 + \varphi_x^2 + \varphi_y^2\right)\right) \theta_3\left(\frac{i\varphi_x\lambda}{2\pi};i\lambda\right) \theta_3\left(\frac{i\varphi_x|\tau|^2\lambda}{2\pi};i\lambda|\tau|^2\right) \\ + \frac{1}{|\tau|} \int_1^\infty d\lambda \ \lambda^{-1/2} \exp\left(-\frac{L_y^2 m_1^2}{4\pi\lambda}\right) \left[\theta_3\left(\frac{\varphi_x}{2\pi};i\lambda\right) \theta_3\left(\frac{\varphi_x}{2\pi};\frac{i\lambda}{|\tau|^2}\right) - 1\right] - \frac{2}{|\tau|}$$
(C5)

where we use the Jacobi Theta function

$$\theta_3(z;\tau) = \sum_{n=-\infty}^{\infty} \exp\left(i\pi\tau n^2 + 2\pi i z n\right)$$
(C6)

For given values of τ , φ_x , and φ_y , we compute the value of $L_y m_1$ by numerically inverting the gap equation $G_1(x, x; m_1^2) = 0$ using the Eq. (C5).

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